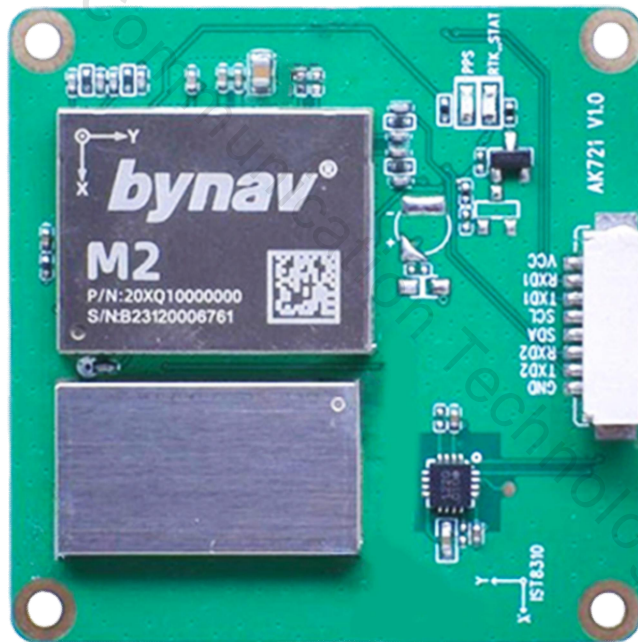


# Dalang

## AK725





# Dalang Communication Technology Co., Ltd Product Specification

|                 |                      |
|-----------------|----------------------|
| Product Name:   | <b>GNSS Receiver</b> |
| Product Model:  | AK725                |
| Version Number: | V 1.0                |
| Revision Date:  | 2024.05.22           |

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# 1 Product Application Scenarios

The AK725 model BeiDou/GPS/Galileo/GLONASS four-constellation dual-frequency RTK integrated module (referred to as the module) is an ultra-low-cost, low-power, high-performance real-time kinematic (RTK) differential positioning module. This module's highly reliable carrier phase differential technology provides real-time centimeter-level positioning accuracy for drones, automobiles, and surveying users. See Figure 1 for details.



Figure 1 Product Application Scenarios

## 2 Features

In this chapter, we will delve into and comprehensively elaborate on the functionalities and operating principles of the AK725, detailing how it plays a pivotal role in various applications as follows:

1. **Stable High-Frequency Performance:** Based on the Beiyun M20 series design, the module can achieve stable and high-precision positioning results even in harsh environments.
2. **Fast:** Supports Beidou/GPS/Galileo/GLONASS four-constellation joint RTK solution, offering fast and reliable initialization capabilities.
3. **High Data Output:** Support up to 10Hz data output, meeting the requirements for applications in dynamic drone environments.
4. **Interference Resistance:** Effectively resists interference from other electronic devices, ensuring clear and accurate positioning signals.
5. **Compatibility:** Fully compatible with Pixhawk and APM flight control systems, ensuring excellent compatibility.
6. **Low Noise:** Utilizes industrial-grade low-noise RF circuitry, providing strong multipath suppression.
7. **High-Precision Magnetometer:** Integrates the industrial-grade iSentek IST8310 magnetometer, offering additional directional support and enhancing the overall accuracy and stability of the navigation system, especially and direction measurements.

### 3 Structural Characteristic

In this section, we will conduct an in-depth analysis of the product's design details, presenting its aesthetic features and precise interface specifications through detailed structural diagrams. This perspective aims to provide a comprehensive framework, thereby enhancing the understanding and perception of the product's architecture. Refer to Figure 2, Table 1.

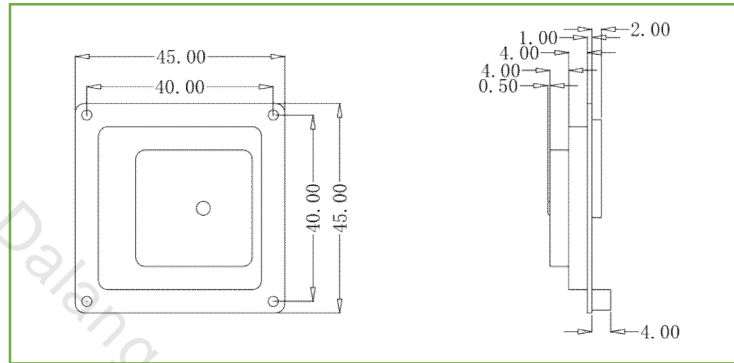


Figure 2 Schematic Diagram

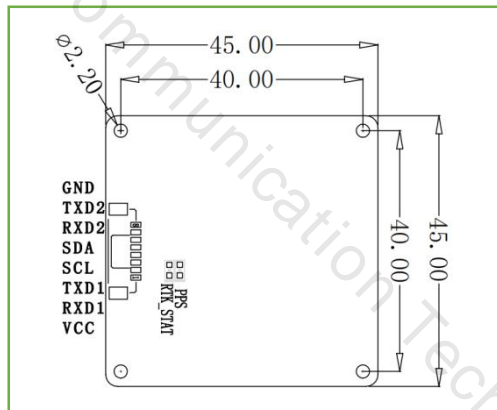


Table 1 PIN Function

| NO. | Signal Name | Signal Description  |
|-----|-------------|---|
| 1   | VCC         | Main power supply input, +3.3V to +5V   |
| 2   | RXD1        | First serial receive data pin, used for receiving serial data streams.  |
| 3   | TXD1        | First serial transmit data pin, used for receiving serial data streams.   |
| 4   | SCL         | Clock line in the I2C communication protocol, used for synchronizing data transfer.                                   |
| 5   | SDA         | Data line in the I2C communication protocol, used for bidirectional data transfer.                                    |
| 6   | RXD2        | Serial receive data pin, similar to RXD1, used for receiving another serial data stream.                              |
| 7   | TXD2        | Serial transmit data pin, similar to TXD1, used for sending another serial data stream.                               |
| 8   | GND         | Ground pin, used for connecting to the circuit's ground, providing the reference voltage needed for the circuit loop. |

Note: Typically, VCC and GND are used for power supply, TX and RX are used for serial communication, while SCL and SDA are used for I<sup>2</sup>C communication. These interfaces allow the receiver to exchange power supply and data with external devices.

## 4 Specifications

In this section, we will provide a detailed list and explanation of the product's chip features, sensitivity, accuracy, operating principles, and other technical details, as detailed in Table 2.

Table 2 Product Specifications

|                                       |                                     |   |      |      |      |
|---------------------------------------|-------------------------------------|---|------|------|------|
| <b>Chip characteristics</b>           | working frequency                   | BDS: B1I、 B2I、 B3I、 B1C、 B2a、 B2b<br>GPS: L1 C/A、 L1C、 L2、 L5<br>GLO: G1、 G2<br>GAL: E1、 E5a、 E5b、 E6<br>QZSS: L1 C/A、 L1C、 L2、 L5、 L6 (CLAS)<br>NavIC: L5<br>SBAS*: L1 C/A |      |      |      |
|                                       | chip                                | Beiyun M20  |      |      |      |
|                                       | Receiving channel                   | 1507 channel  |      |      |      |
| <b>Time To First Fix</b>              | cold boot                           | ≤30s  |      |      |      |
|                                       | Hot start                           | ≤5s   |      |      |      |
|                                       | Re capture                          | ≤1s   |      |      |      |
|                                       | RTK initialization                  | ≤ 5 s   |      |      |      |
| <b>Accuracy</b>                       | Horizontal positioning accuracy     | Single point: 1.5mCEP   |      |      |      |
|                                       |                                     | RTK: 1.0 cm + 1 ppmCEP  |      |      |      |
|                                       | Elevation positioning accuracy      | Single point: 2.5mCEP   |      |      |      |
|                                       |                                     | RTK: 1.5 cm + 1 ppmCEP  |      |      |      |
|                                       | Observation accuracy (RMS)          | BDS   | GPS  | GLO  | GAL  |
|                                       | B1I/B1C/L1C/L1 CA/E1/G1 pseudorange | 10cm  | 10cm | 10cm | 10cm |
| B1I/B1C/L1C/L1 CA/E1/G1 Carrier Phase | 1mm                                 | 1mm   | 1mm  | 1mm  |      |
| B2I/B2a/B2b/L5/E5a/E5b pseudorange    | 10cm                                | 10cm  | 10cm | 10cm |      |
| B2I/B2a/B2b/L5/E5a/E5b                | 1mm                                 | 1mm   | 1mm  | 1mm  |      |

|                                  |                            |                                |      |      |      |
|----------------------------------|----------------------------|--------------------------------|------|------|------|
|                                  | Carrier Phase              |                                |      |      |      |
|                                  | B3I/L2/G2 pseudorange      | 10cm                           | 10cm | 10cm | 10cm |
|                                  | B3I/L2/G2 Carrier Phase    | 1mm                            | 1mm  | 1mm  | 1mm  |
|                                  | Speed accuracy             | 0.03m/s                        |      |      |      |
|                                  | Timing accuracy            | ≤20 ns                         |      |      |      |
| <b>Output data</b>               | Baud rate                  | 115200bps (default)            |      |      |      |
|                                  | Output interface           | TTL                            |      |      |      |
|                                  | Output Protocol            | NMEA,RTCM3.3, BYNAV            |      |      |      |
|                                  | update frequency           | Default 1Hz (1Hz-10Hz)         |      |      |      |
|                                  | Carrier phase output       | Support, output RAWX statement |      |      |      |
|                                  | FLASH                      | built-in                       |      |      |      |
| <b>Working conditions</b>        | speed                      | <550m/s                        |      |      |      |
|                                  | Gravitational acceleration | <4g                            |      |      |      |
| <b>Environment</b>               | working temperature        | -40°C-85°C                     |      |      |      |
|                                  | Storage temperature        | -40°C-85°C                     |      |      |      |
| <b>Electrical specifications</b> | working voltage            | 3V~5.5V DC                     |      |      |      |
|                                  | power waste                | <800mW@3.3V                    |      |      |      |
| <b>Physical parameters</b>       | size                       | 45*11.5mm                      |      |      |      |
|                                  | weight                     | 35.8g                          |      |      |      |
|                                  | Connector                  | GH1.25mm 8pin                  |      |      |      |

## 5 Product Photos

In this chapter, we will showcase real-life images of the product, as shown in Figure 4. These images provide a detailed view of our product from various angles and perspectives. We believe that through authentic representation, we can better convey the value and concept of the product, thereby enhancing your trust and satisfaction.

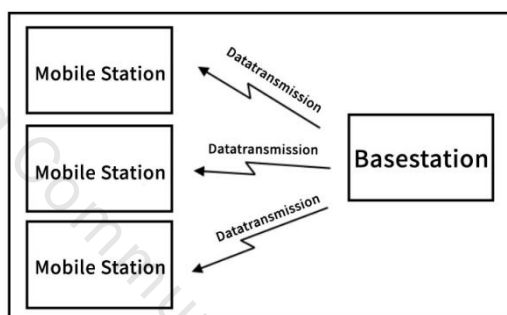


Figure 4 Product Images

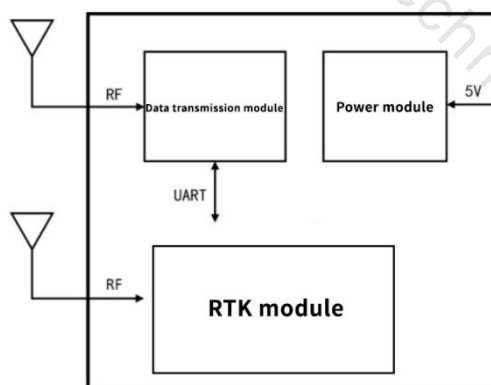
## 6 Typical Applications

### 6.1 Application of high-precision positioning for medium and short distances

In high-precision positioning applications for medium to short distances (<3km), the module can be combined with a data transmission module to form a complete high-precision positioning system with only a small amount of external circuits. It is suitable for applications with a large number of mobile stations in a small range, and the module is fully compatible with other automatic flight control systems such as Pixhawk and APM. The schematic diagram is as follows:



The reference station is stationary and fixed, and differential data is broadcasted to all mobile stations through a data transmission module. The circuit diagrams of the mobile station and the reference station are as follows:



3) If the antenna coordinates have been accurately determined through other surveying methods, please use the # set position command to input the antenna coordinates into the reference station module in latitude, longitude, and altitude format;

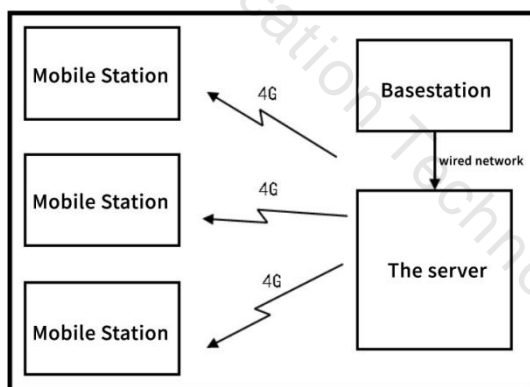
4) If the antenna coordinates are unknown, please wait patiently for about 5 minutes. The module will calculate the antenna position as accurately as possible. After the calculation is c

ompleted, the differential data port will begin to output data. At this point, the base station has already recorded the coordinates and broadcasted them wirelessly to ensure that the base station does not lose power, as the coordinates will be recalculated after a power outage and the repeatability of the mobile station measurement points cannot be guaranteed;

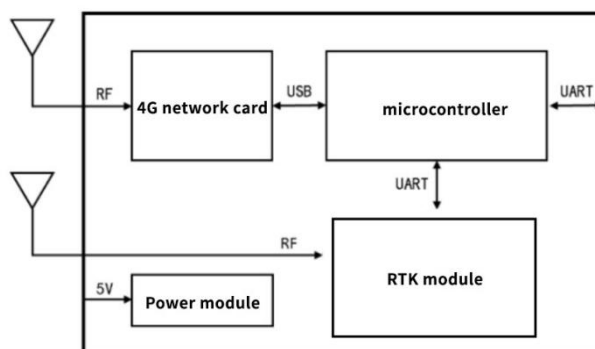
5) Install the mobile station antenna on the mobile carrier, confirm receipt of differential data, and wait for about 120 seconds to obtain high-precision positioning results.

## 6.2 Application of Medium to Long Range High Precision Positioning

In the application of high-precision positioning over medium to long distances (<10km), common data transmission modules are difficult to provide reliable differential data connections and suffer from serious packet loss problems. For this purpose, the company provides a solution based on 4G network (as shown in the figure below). The benchmark station sends differential data to the server through a wired network and is cached by the server. Mobile stations access servers through 4G networks to obtain differential data. This solution can greatly expand the coverage area of base stations, and mobile stations equipped with 4G network cards can simultaneously transmit positioning results back to designated servers.



The circuit diagram of the mobile station is as follows:



In practical applications, the number of mobile stations that a server can access simultaneously is limited only by server performance and is more suitable for a large number of users. Requirements between the server and the base station: the server can be directly accessed from the public network (with a public IP address), and a network connection can be established between the base station and the server (either through the public network or local area network).

### 6.3 High precision positioning application without reference station

In high-precision positioning applications without reference stations, the module needs to cooperate with the 4G communication module to obtain differential data. We provide Qianxun with differential data sources nationwide, and users can obtain high-precision positioning results without deploying base stations. The circuit diagram is as follows:

